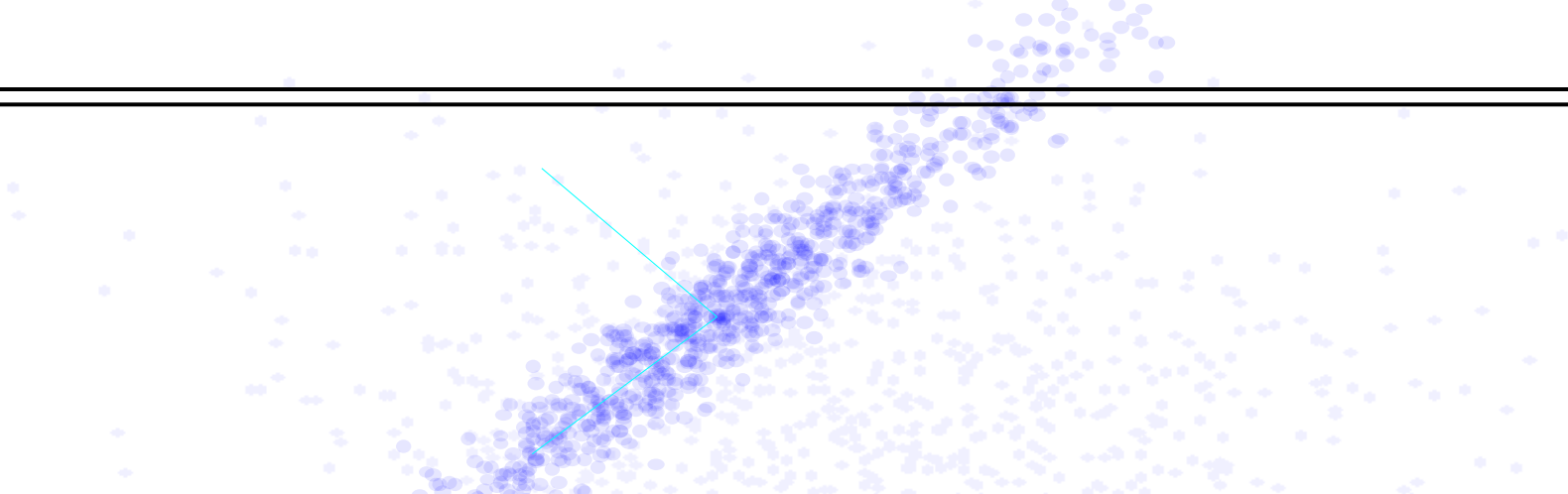


Principal Component Analysis and Independent Component Analysis in Neural Networks



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CS 152 – Neural Networks
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Outline

- Review PCA and ICA
- Neural PCA Models
- Neural ICA Models
- Experiments and Results
- Implementations
- Summary/Conclusion
- Questions

Principal Component Analysis

- PCA identifies an m dimensional explanation of n dimensional data where $m < n$.
- Originated as a statistical analysis technique.
- PCA attempts to minimize the reconstruction error under the following restrictions
 - Linear Reconstruction
 - Orthogonal Factors
- Equivalently, PCA attempts to maximize variance.

Independent Component Analysis

- Also known as Blind Source Separation.
- Proposed for neuromimetic hardware in 1983 by Herault and Jutten.
- ICA seeks components that are independent in the statistical sense.

Two variables x, y are *statistically independent* iff $P(x \cap y) = P(x)P(y)$.

Equivalently,

$$E\{g(x)h(y)\} - E\{g(x)\}E\{h(y)\} = 0$$

where g and h are any functions.

Independent Component Analysis

Given m signals of length n , construct the data matrix

$$X = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{pmatrix}.$$

We assume that X consists of m sources such that

$$X = AS$$

where A is an unknown m by m mixing matrix and S is m independent sources.

Independent Component Analysis

ICA seeks to determine a matrix W such that

$$Y = BX$$

where W is an m by m matrix and Y is the set of independent source signals, i.e. the independent components.

$$B \approx A^{-1} \Rightarrow Y = A^{-1}AX = X$$

- Note that the components need not be orthogonal, but that the reconstruction is still linear.

PCA with Neural Networks

- Most PCA Neural Networks use some form of Hebbian learning.

“Adjust the strength of the connection between units A and B in proportion to the product of their simultaneous activations.”

$$w_{k+1} = w_k + \beta_k (y_k x_k)$$

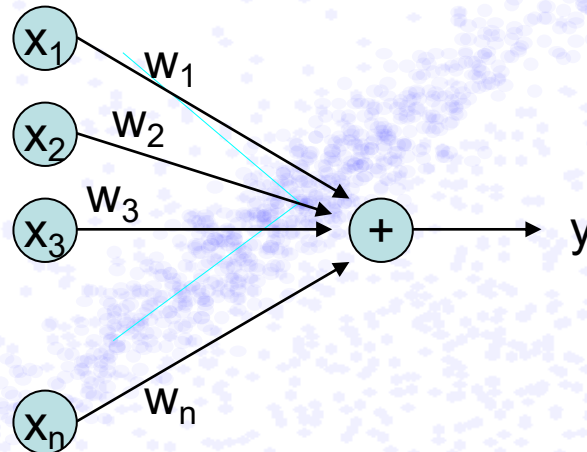
- Applied directly, this equation is unstable.

$$\|w_k\|^2 \rightarrow \infty \text{ as } k \rightarrow \infty$$

- Important Note: neural PCA algorithms are unsupervised.

PCA with Neural Networks

- Another fix: Oja's rule.
- Proposed in 1982 by Oja and Karhunen.

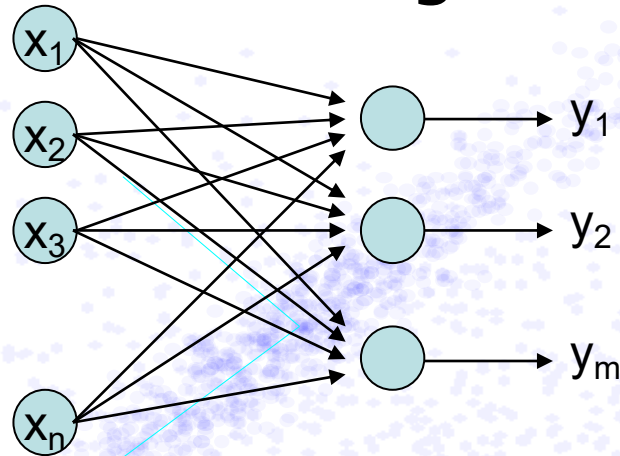


$$w_{k+1} = w_k + \beta_k (y_k x_k - y_k^2 w_k)$$

- This is a linearized version of the normalized Hebbian rule.
- Convergence, as $k \rightarrow \infty$, $w_k \rightarrow e_1$.

PCA with Neural Networks

- Generalized Hebbian Algorithm



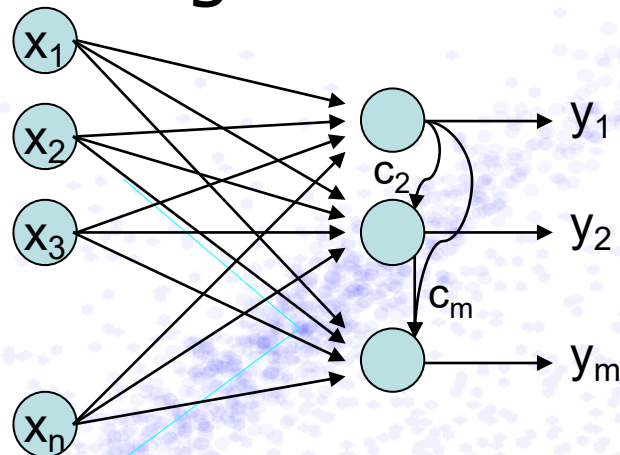
$$y = Wx$$

$$\Delta w_{ij,k} = \beta_k y_{ik} x_{jk} - \beta_k y_{ik} \sum_{l \leq i} y_{lk} w_{lj,k}$$

$$\Delta W = \beta_k y x^T - \beta_k W \text{LT}(y y^T)$$

PCA with Neural Networks

- APEX Model: Kung and Diamantaras



$$y = Wx - Cy \Leftrightarrow y = (I+C)^{-1}Wx \approx (I-C)Wx$$

$$C = \begin{bmatrix} 0 & 0 & 0 & \dots & 0 \\ c_{21} & 0 & 0 & \dots & 0 \\ c_{31} & c_{32} & 0 & \dots & 0 \\ \vdots & & \ddots & & \vdots \\ c_{m-1,1} & \dots & c_{m-1,m-2} & 0 & 0 \\ c_{m,1} & \dots & \dots & c_{m,m-1} & 0 \end{bmatrix}$$

PCA with Neural Networks

- APEX Learning

$$\Delta w_{i,j,k} = \beta_k (y_{ik} x_{jk} - y_{ik}^2 w_{i,j,k})$$

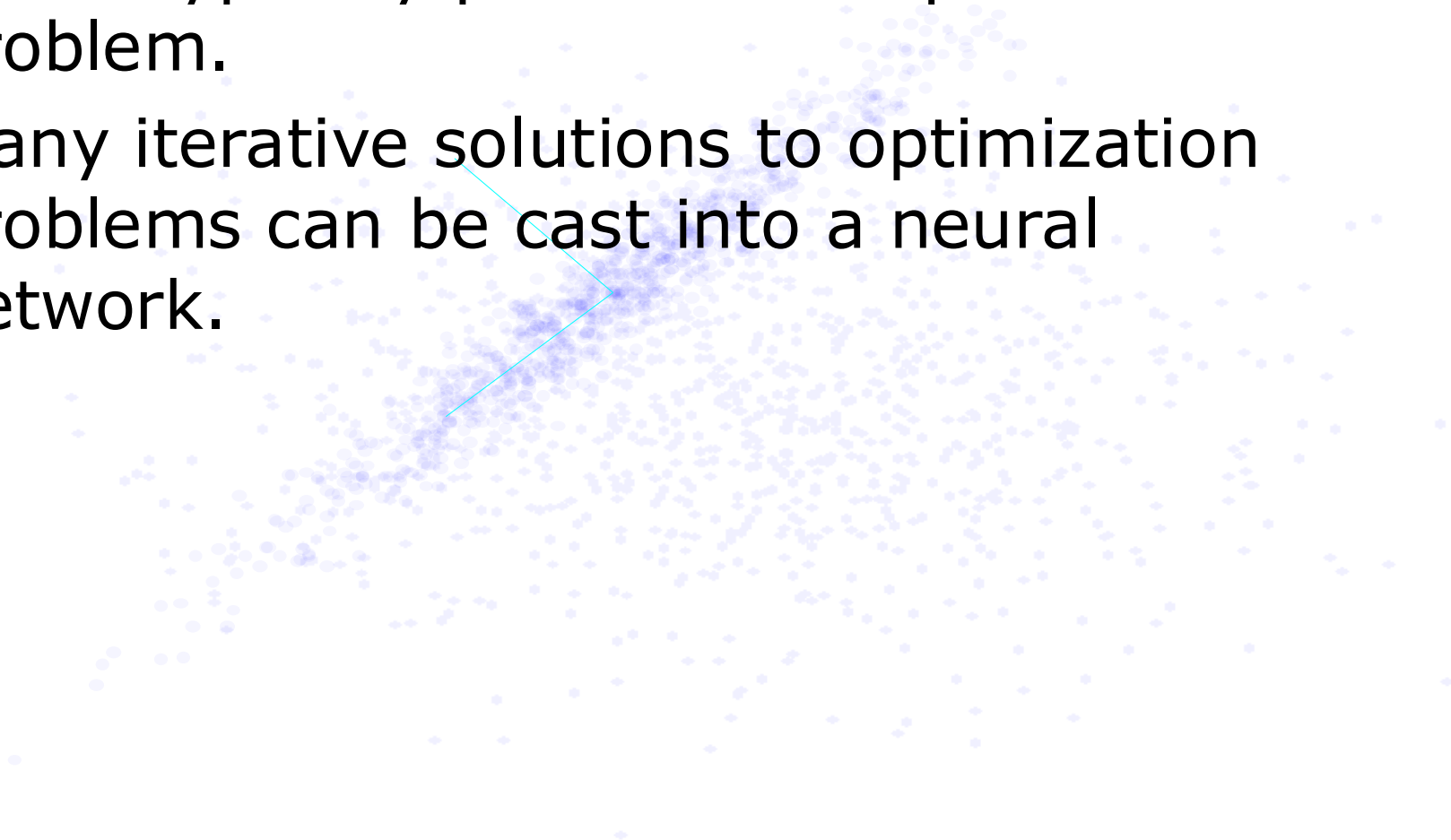
$$\Delta c_{i,j,k} = \beta_k (y_{ik} y_{jk} - y_{ik}^2 c_{i,j,k})$$

- Properties of APEX model:

- Exact principal components
- Local updates, Δw_{ab} only depends on x_a, x_b, w_{ab}
- “-Cy” acts as an orthogonalization term

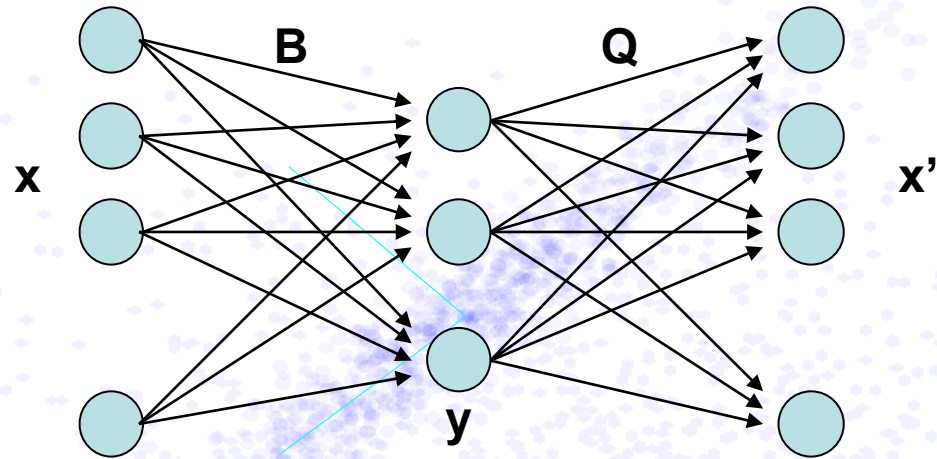
Neural ICA

- ICA is typically posed as an optimization problem.
- Many iterative solutions to optimization problems can be cast into a neural network.



Feed-Forward Neural ICA

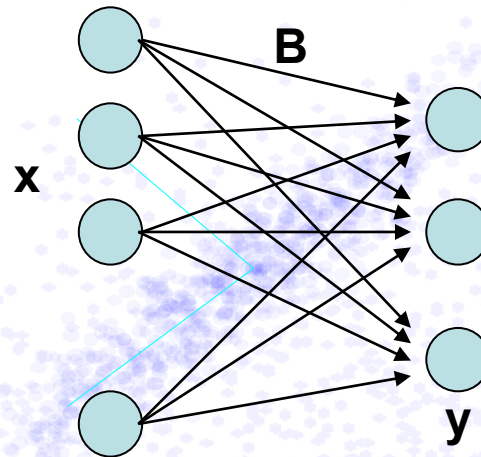
General Network Structure



1. Learn B such that $y = Bx$ has independent components.
2. Learn Q which minimizes the mean squared error reconstruction.

Feed-Forward Neural ICA

General Network Structure



1. Learn B such that $y = Bx$ has independent components.

Neural ICA

- Herault-Jutten: local updates

$$B = (I+S)^{-1}$$

$$S_{k+1} = S_k + \beta_k g(y_k) h(y_k^T)$$

$$g = t, h = t^3; g = \text{hardlim}, h = \text{tansig}$$

- Bell and Sejnowski: information theory

$$B_{k+1} = B_k + \beta_k [B_k^{-T} + z_k x_k^T]$$

$$z(i) = \partial/\partial u(i) \partial u(i)/\partial y(i)$$

$$u = f(Bx); f = \text{tansig}, \text{ etc.}$$

Neural ICA

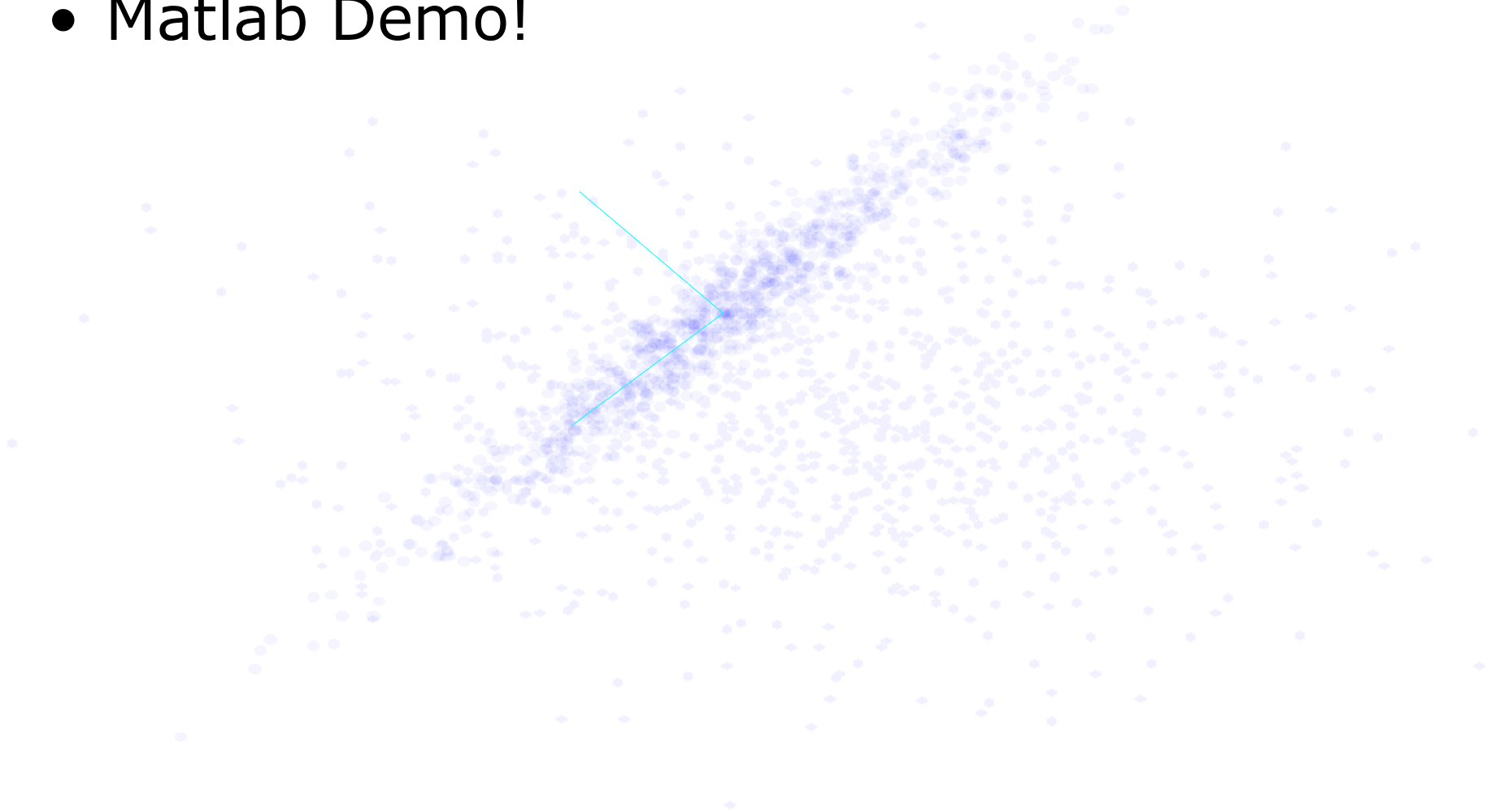
- EASI (Equivariant Adaptive Separation via Independence): Cardoso et al

$$\mathbf{B}_{k+1} = \mathbf{B}_k - \beta_k [\mathbf{y}_k \mathbf{y}_k^T - \mathbf{I} + \mathbf{g}(\mathbf{y}_k) \mathbf{h}(\mathbf{y}_k)^T - (\mathbf{y}_k) \mathbf{g}(\mathbf{y}_k)^T] \mathbf{B}_k$$

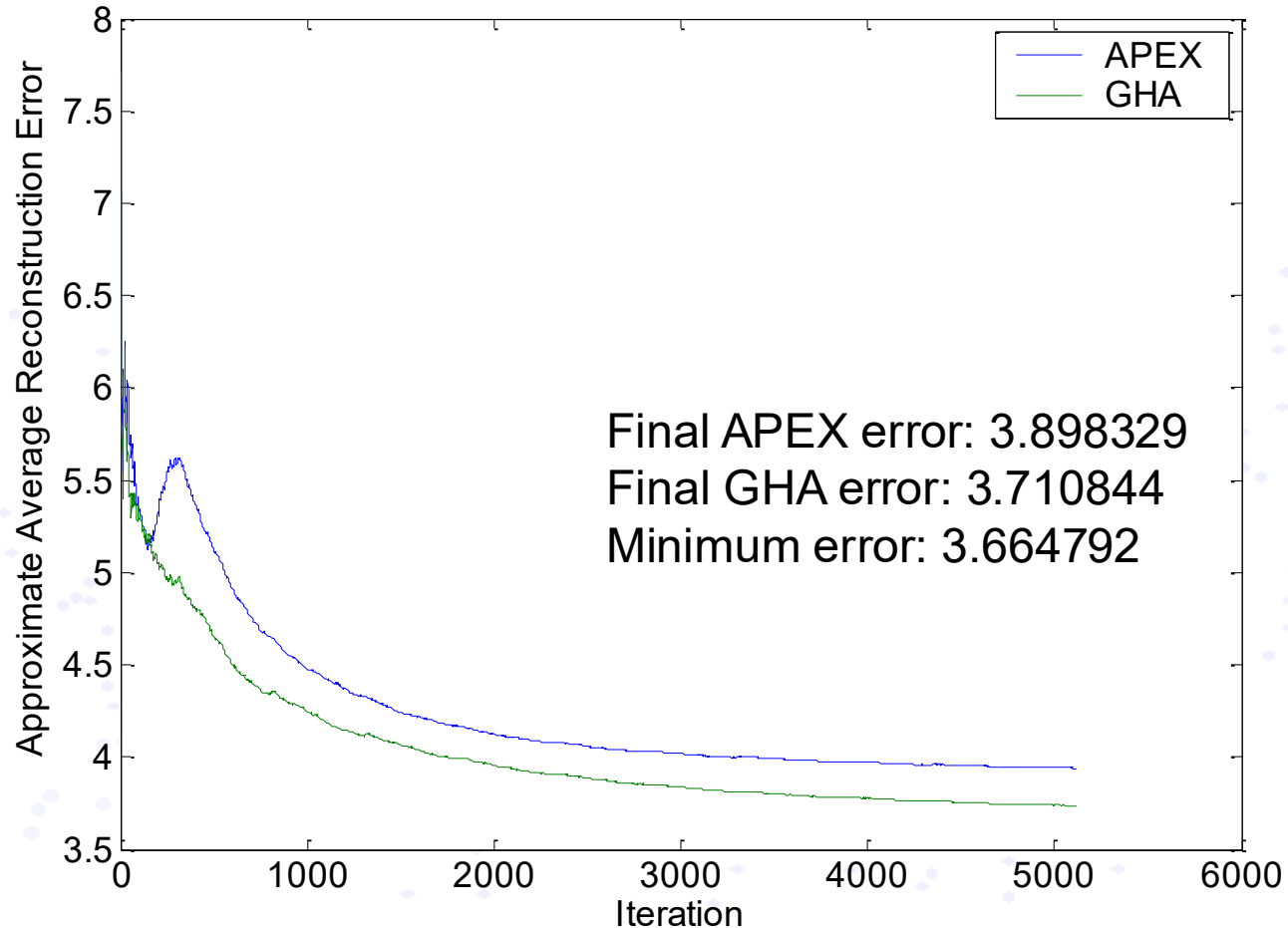
$$\mathbf{g} = \mathbf{t}, \mathbf{h} = \text{tansig}(\mathbf{t})$$

Oja's Rule in Action

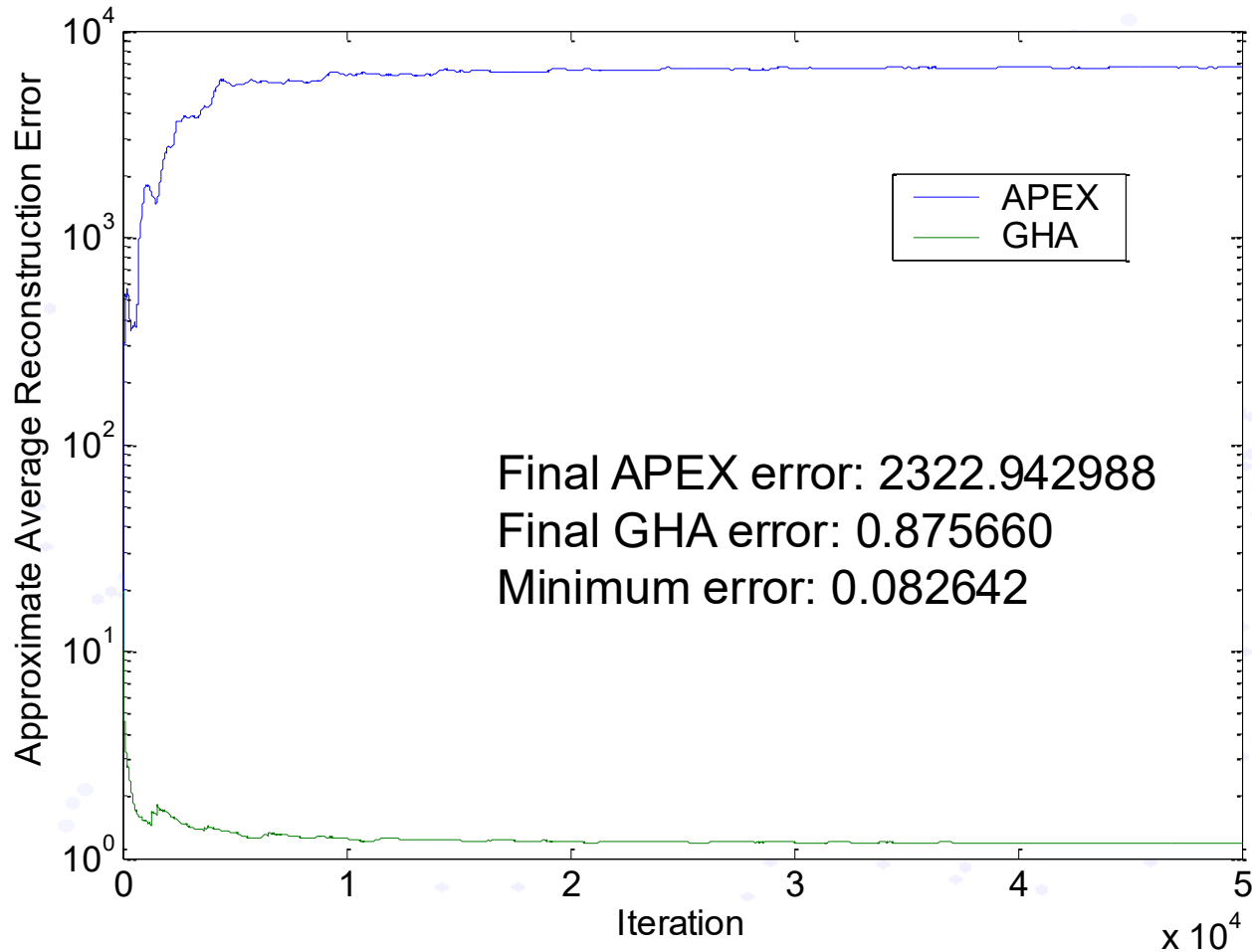
- Matlab Demo!



PCA Error Plots – Close Eigenvalues

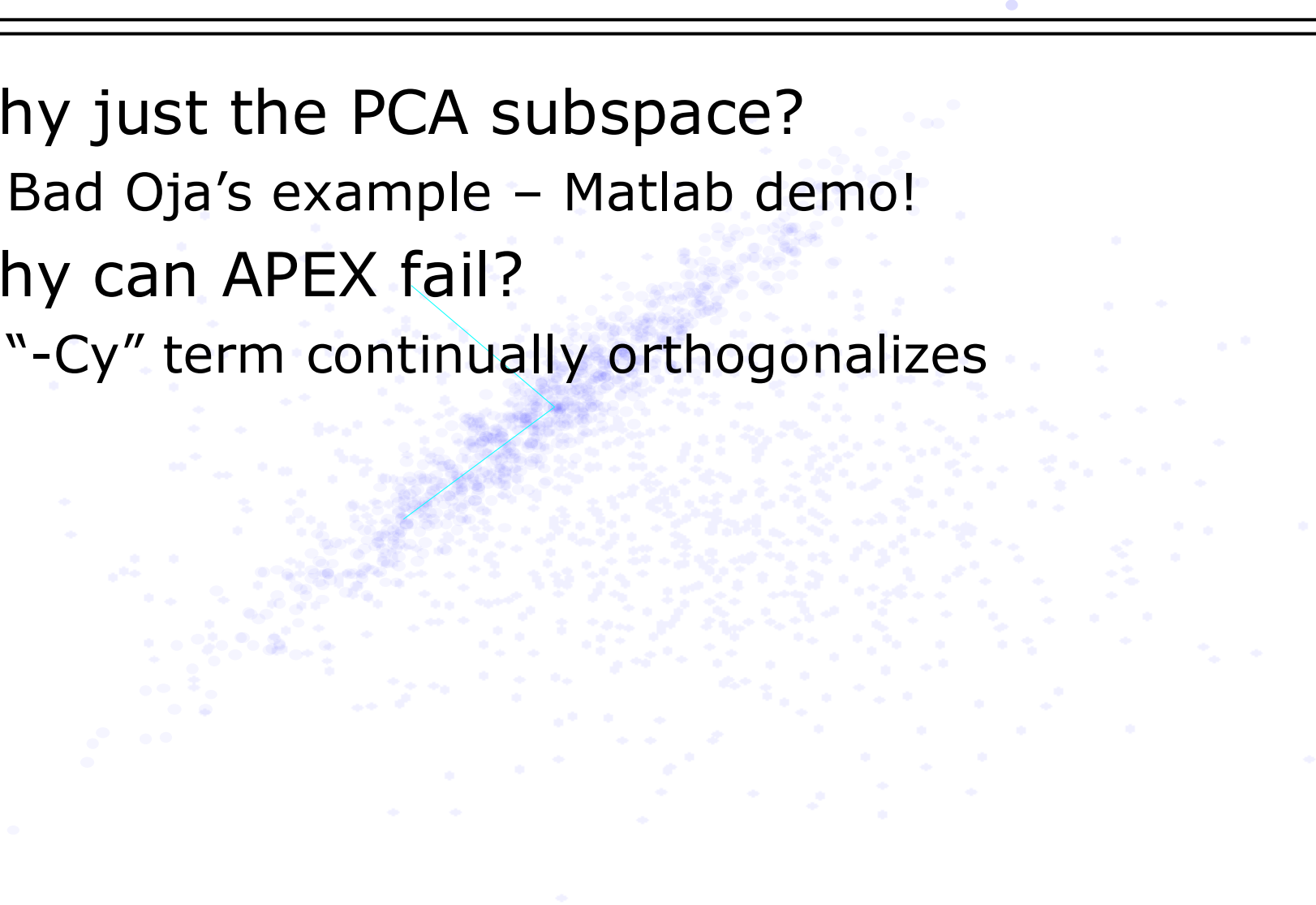


PCA Error Plots – Separate Eigenvalues



Observations

- Why just the PCA subspace?
 - Bad Oja's example – Matlab demo!
- Why can APEX fail?
 - “-Cy” term continually orthogonalizes



ICA Image Example



ICA Image Example

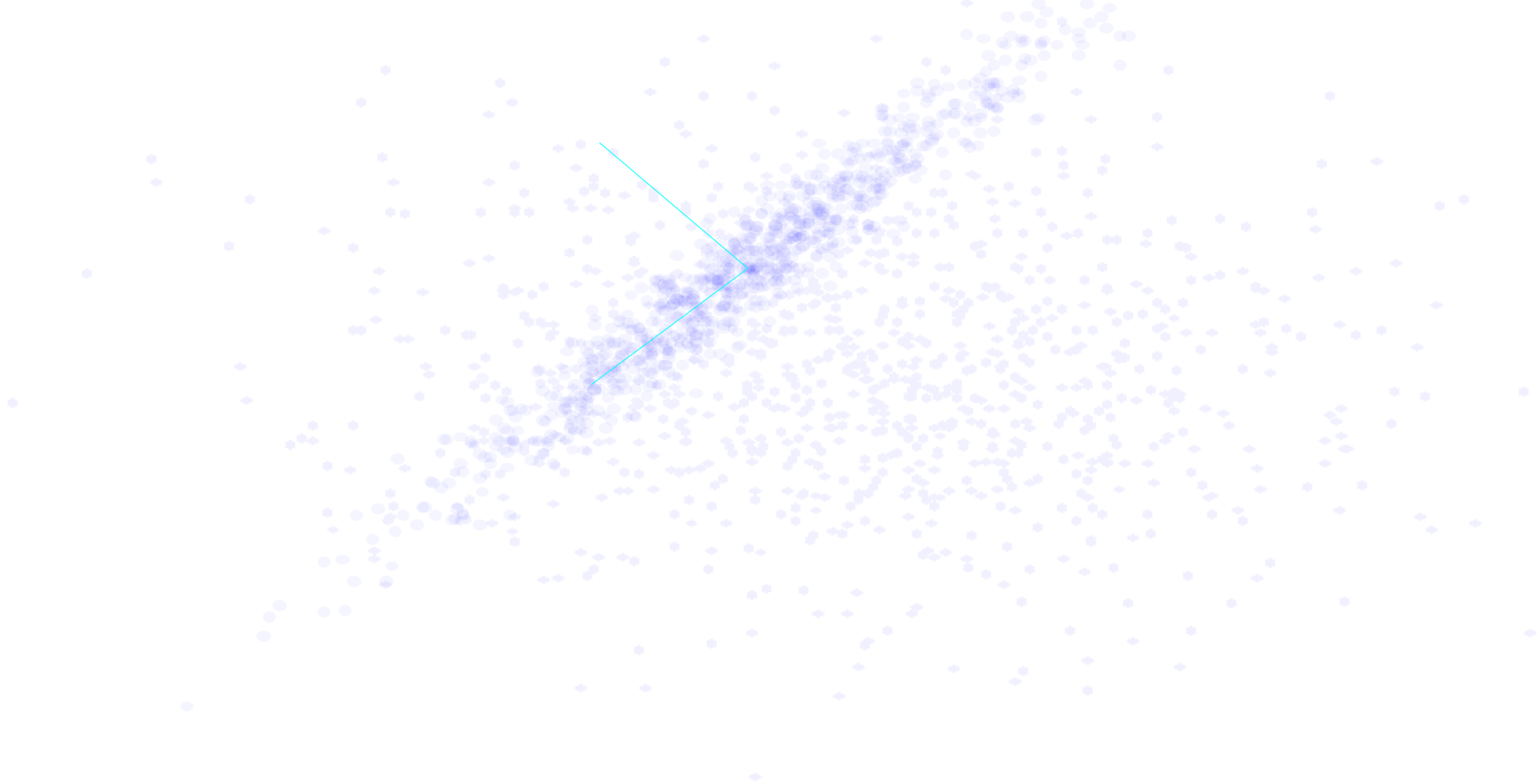


Bell and Sejnowski

EASI

Real World Data

- 8 channel ECG from pregnant mother



Implementation

- Matlab sources for each neural algorithm, and supporting functions
 - PCA: oja.m; gha.m; apex.m
 - ICA: hj.m; easi.m; bsica.m
 - Evaluation: pcaerr.m
 - Demos: fetal_plots.m; pca_error_plots.m; ojademo.m; ica_image_demo.m
 - Data generators: evalpca.m; evalica.m

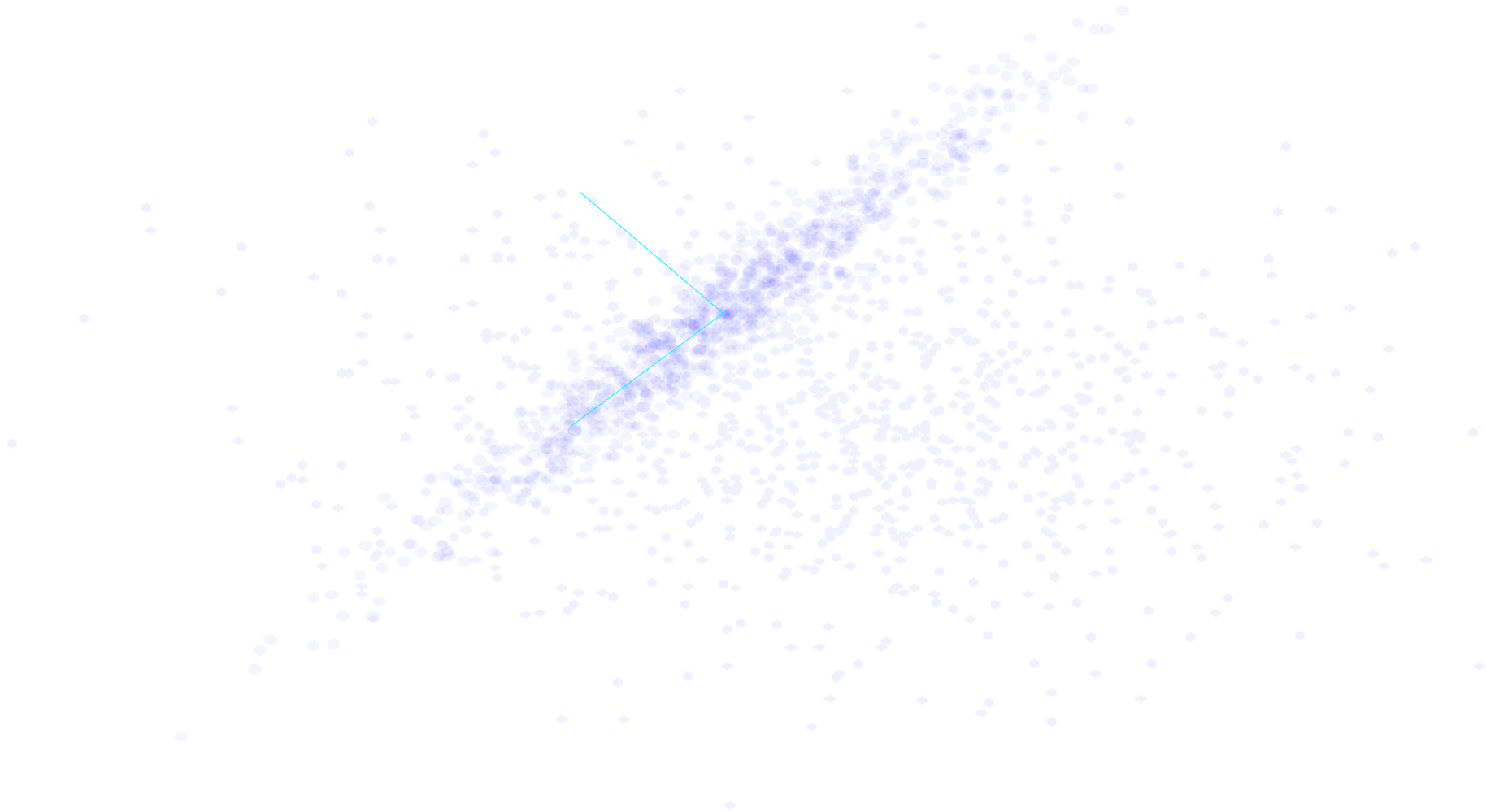
Future Work

- Investigate adaptive learning and changing separations
 - Briefly examined this; the published paper on ICA adjusted the learning rate correctly, but didn't converge to a separation.
- Convergence of PCA algorithms based on eigenvalue distribution?
- Use APEX to compute "more" components than desired?

Summary

- Neural PCA:
 - Algorithms work “sometimes.” They tend to find the PCA subspace rather than the exact PCA components
 - GHA is better than APEX
- Neural ICA:
 - Algorithms converge to something reasonable.
 - Bell and Sejnowski’s ICA possibly superior to EASI.

Questions?



References

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